

Introduction to Biosignal Detection

Wenxi Chen

Biomedical Information Engineering Lab.

The University of Aizu

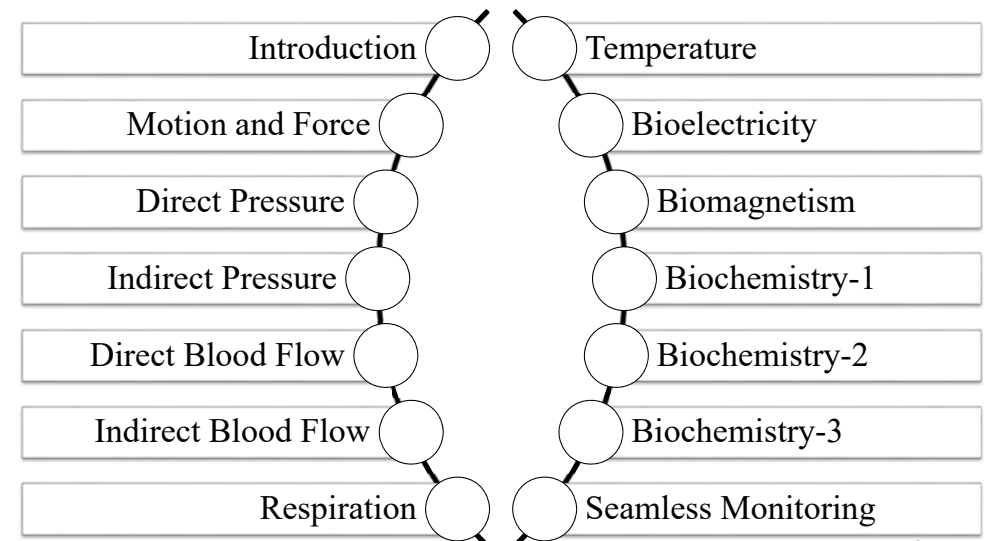
Synopsis

- Introductory knowledge on various physiological information in human body
- Fundamental science and engineering principles, such as physical and chemical, electrical and electronic, in measurement of various biosignals, and basic concepts of biomedical instrumentation
- Special aspects of sensing and detecting in biological system that are different from the industrial application

Biosignal Detection?

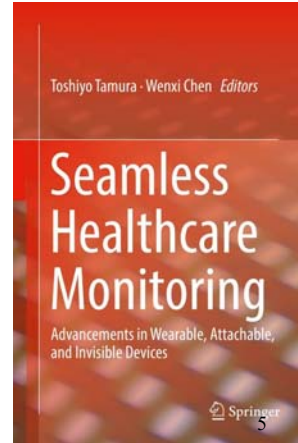
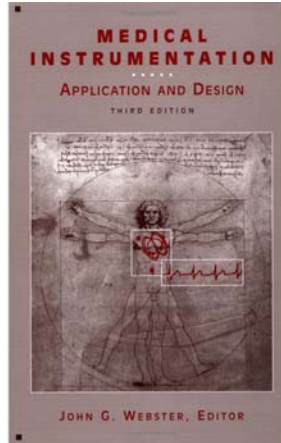
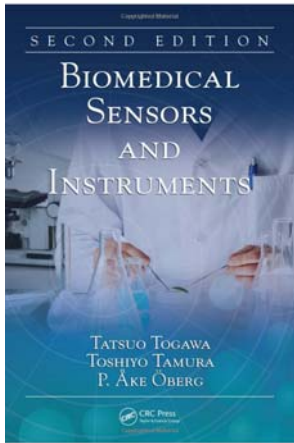
- **Biosignal**
 - Chemical or physical quantities that characterize the property or state of human biological condition
 - A wide spectrum in time and frequency domains
- **Detection**
 - Apply various science and engineering principles and modalities to determine or measure these quantities
- **Biosignal detection**
 - A procedure by which we can determine or measure these quantities

Contents



Handouts and Books

- <http://i-health.u-aizu.ac.jp/IBSD>



1. Introduction

- Various biosignals
- Measurement methods
- Particularities
- Static and dynamic characteristics
- Signal and noise
- Types of noise
- Absolute quantity
- Types of error

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No.1

Various Biosignals

Biosignal		Range	Freq., Hz	Sensor
Ballistocardiogram (BCG)		0-7 mg	0-40	Accelerometer, strain gage
		0-100 μ m	0-40	Displacement (LVDT, Linear Variable Differential Transformer)
Bladder pressure		1-100 cm H ₂ O	0-10	Strain gage manometer
Blood flow		1-300 ml/s	0-20	Flowmeter (electromagnetic or ultrasonic)
Blood pressure, arterial	Direct	10-400 mm Hg	0-50	Strain gage manometer
	Indirect	25-400 mm Hg	0-60	Cuff, auscultation
Blood pressure, venous		0-50 mm Hg	0-50	Strain gage

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No.2

Biosignal		Range	Freq., Hz	Sensor
Blood gases	PO ₂	30-100 mm Hg	0-2	Specific electrode, volumetric or manometric
	PCO ₂	40-100 mm Hg	0-2	
	PN ₂	1-3 mm Hg	0-2	
	PCO	0.1-0.4mm Hg	0-2	
Blood pH		6.8-7.8 pH units	0-2	Specific electrode
Cardiac output		4-25 liter/min	0-20	Dye dilution, Fick
Electrocardiogram (ECG)		0.5-4 mV	0.01-250	Skin electrodes
Electroencephalogram (EEG)		5-300 μ V	0-150	Scalp electrodes

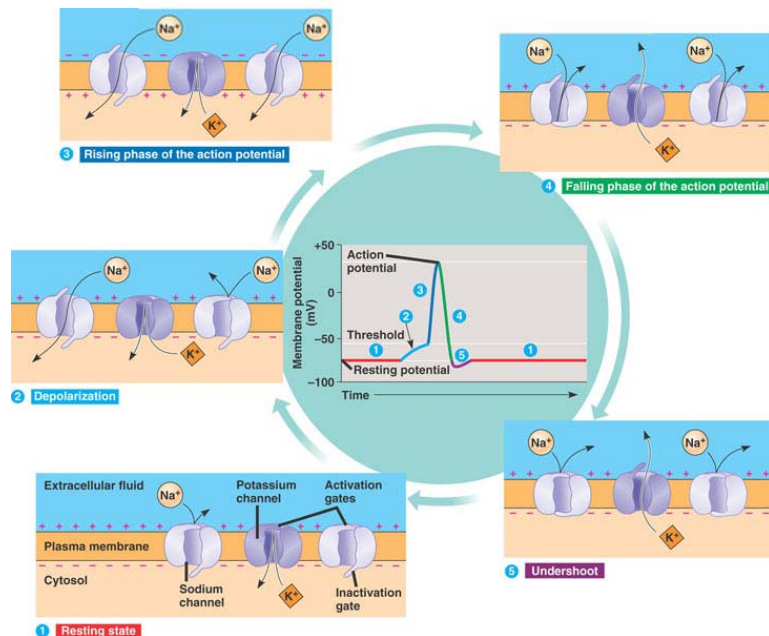
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Biosignal	Range	Freq., Hz	Sensor
Electrocorticogram	10-5000 μV	0-150	Brain-surface or depth electrodes
Electromyogram (EMG)	0.1-5 mV	0-10,000	Needle electrodes, skin electrodes
Electrooculogram (EOG)	50-3500 μV	0-50	Contact electrodes
Electroretinogram (ERG)	0-900 μV	0-50	Contact electrodes
Galvanic skin response (GSR)	1-500 k Ω	0.01-1	Skin electrodes
Electrogastrogram (EGG)	10-1000 μV	0-1	Skin surface electrodes
	0.5-80 mV	0-1	Stomach surface electrodes
Gastrointestinal pressure	0-100 cm H ₂ O	0-10	Strain gage
Gastrointestinal forces	1-50 g	0-1	Displacement system, LVDT
Gastric pH	3 - 13 pH units	0-1	pH electrode, antimony electrode ₉

Biosignal		Range	Freq., Hz	Sensor
Nerve potentials		0.01- 3 mV	0-10,000	Surface or needle electrodes
Phonocardiogram (PCG)		Dynamic range 80 dB, threshold about 100 μPa	5-2000	Microphone
Plethysmogram (volume change)		Varies with organ	0-30	Displacement chamber or impedance change
Respiratory functions	Flow rate	0-600 liter/min	0-40	Pneumotachograph head and differential pressure
	Respiratory rate	2-50 breaths/min	0.1-10	Strain gage on chest, impedance, nasal thermistor
	Tidal volume	50-1000 ml/breath	0.1-10	Above methods
Body temperature		32-40 °C 90-104 °F	0-0.1	Thermistor, thermocouple

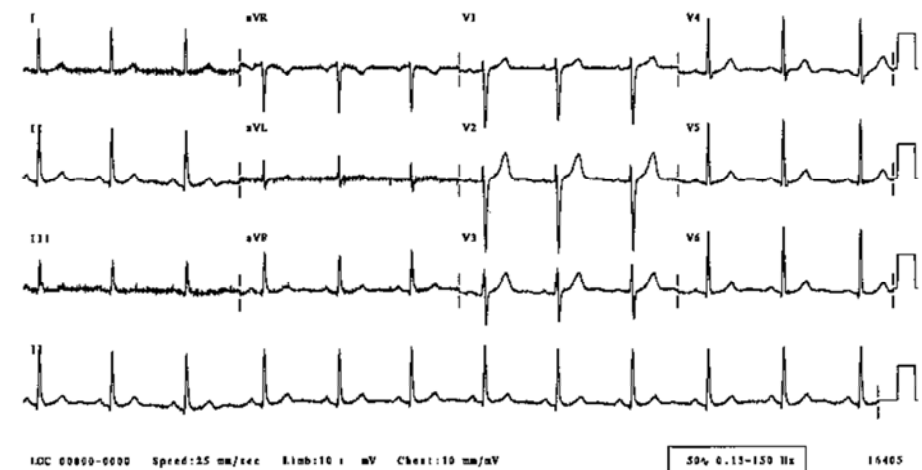
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Action Potential



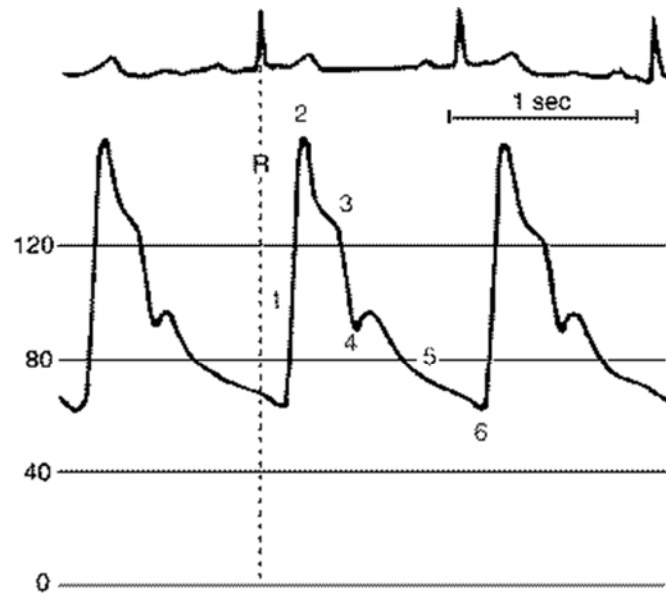
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12-Lead ECG



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ECG and ABP



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ECG and Respiration



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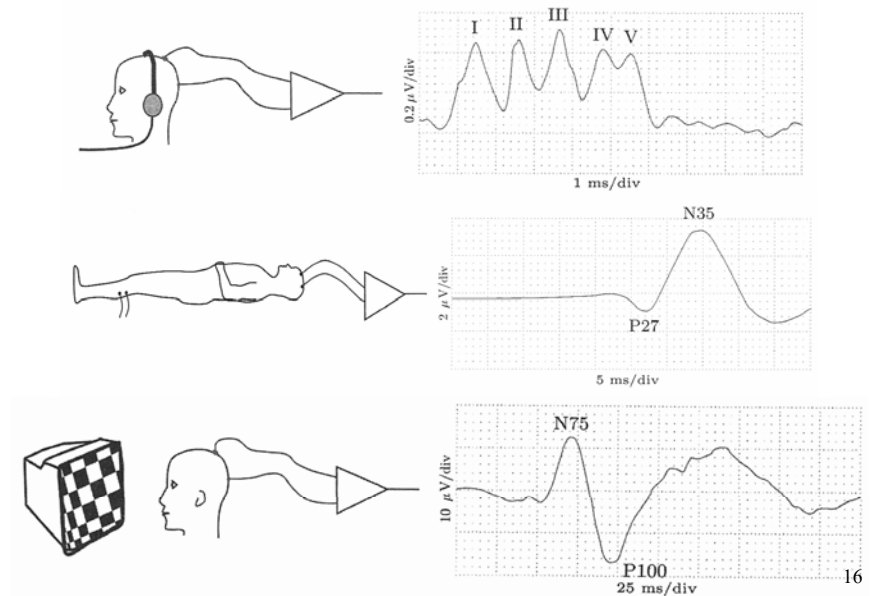
Position of electrode

Spontaneous EEG



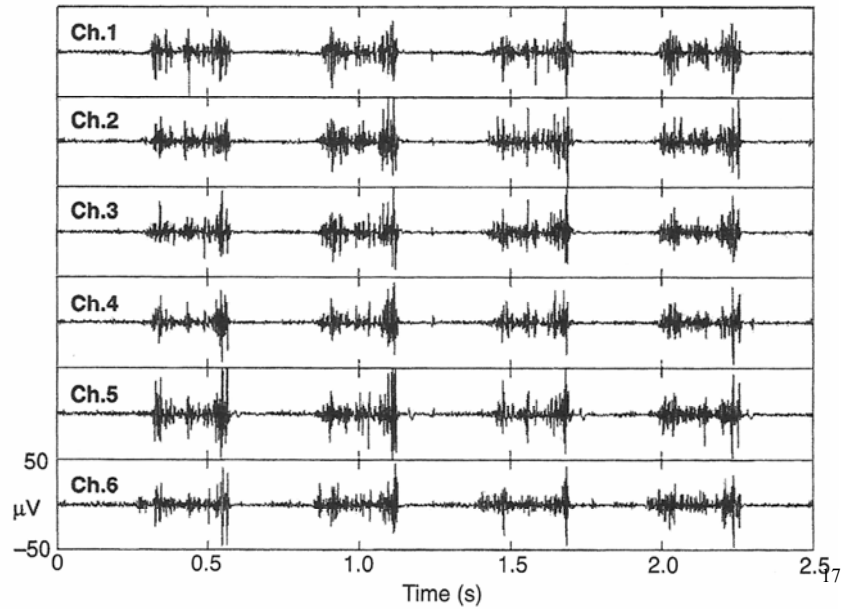
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Evoked EEG

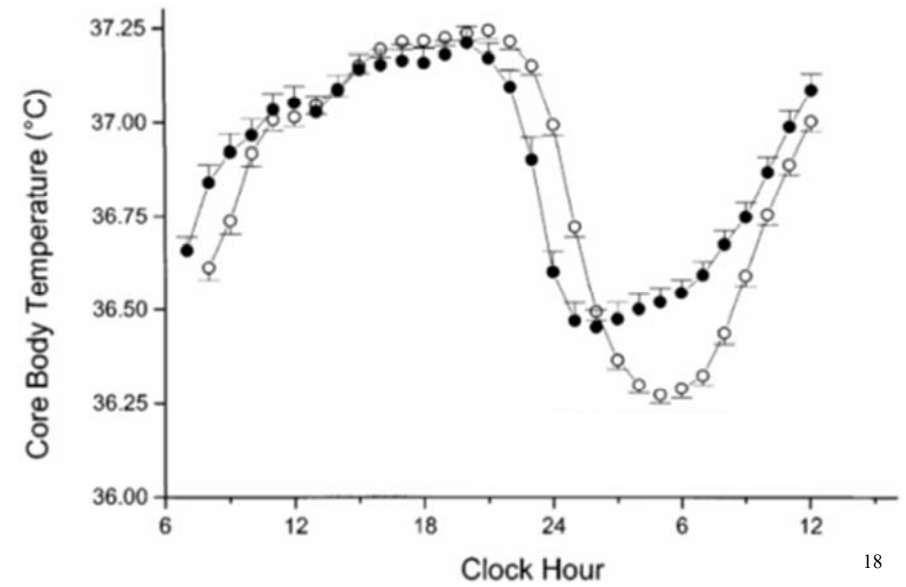


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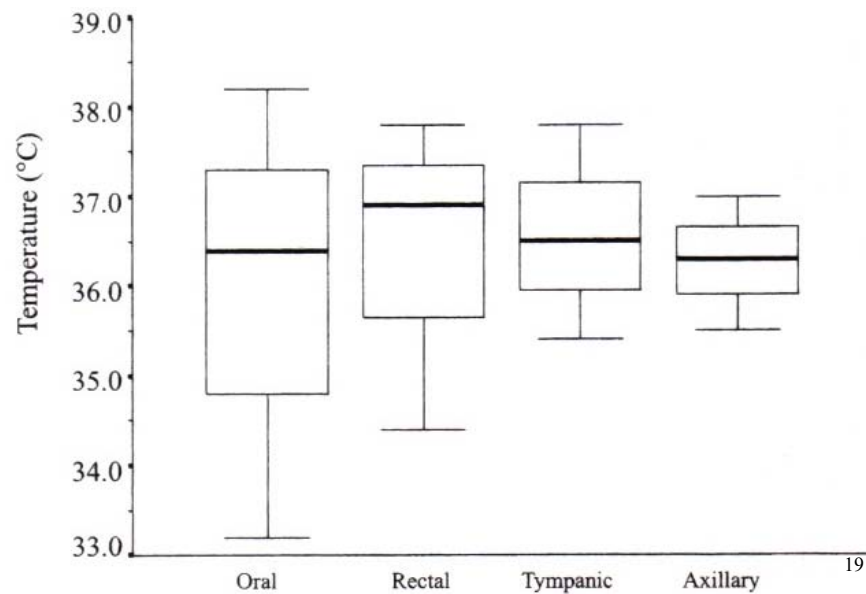
EMG



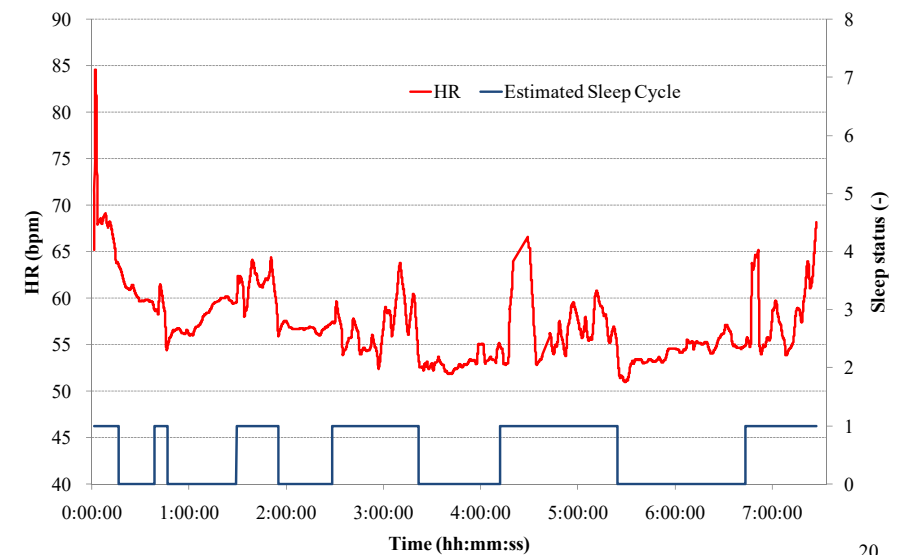
Body Temperature with Time



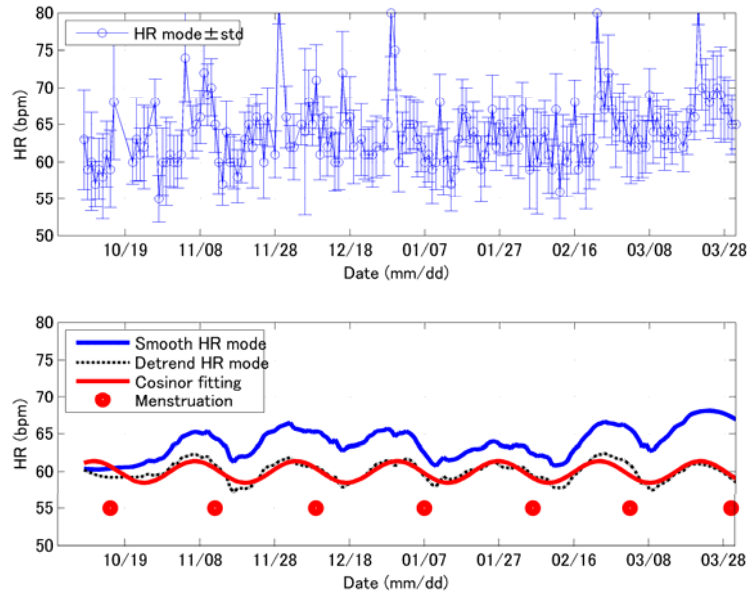
Body Temperature with Place



Daily HR and Sleep Cycle

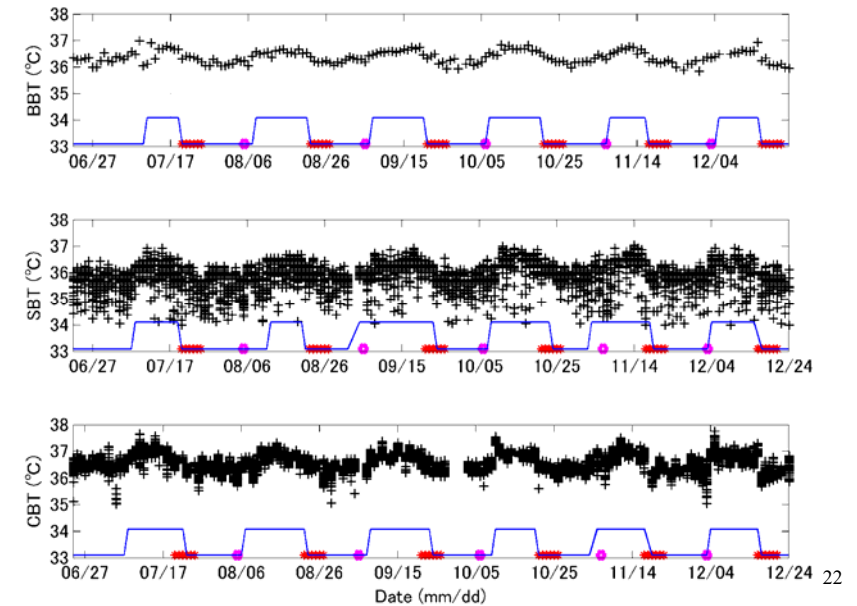


Daily HR and Menstrual Cycle



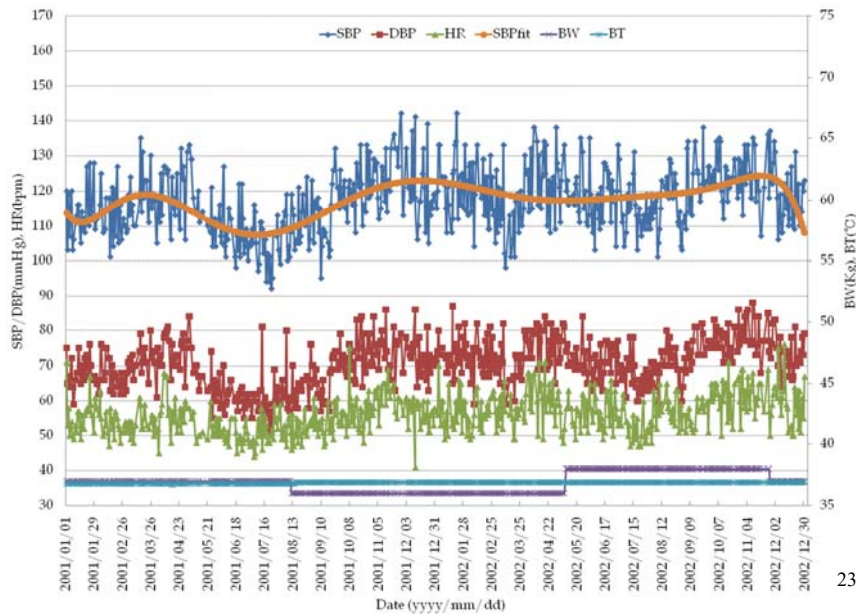
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Daily BTs and Menstrual Cycle

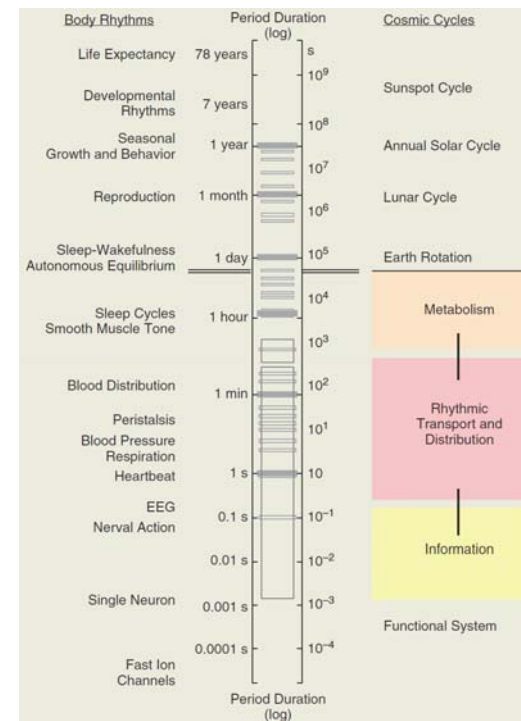


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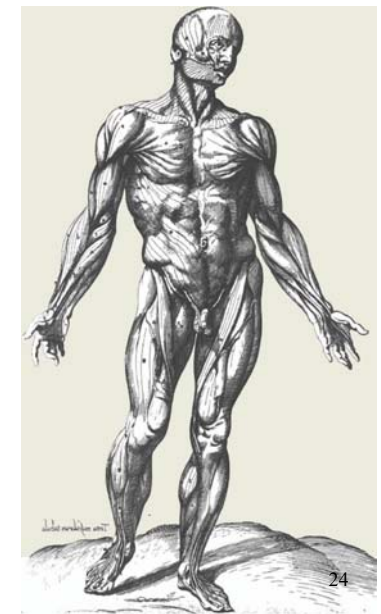
Daily BP, HR and Biorhythm



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Wide spectrum of various physiological information in time and frequency domains



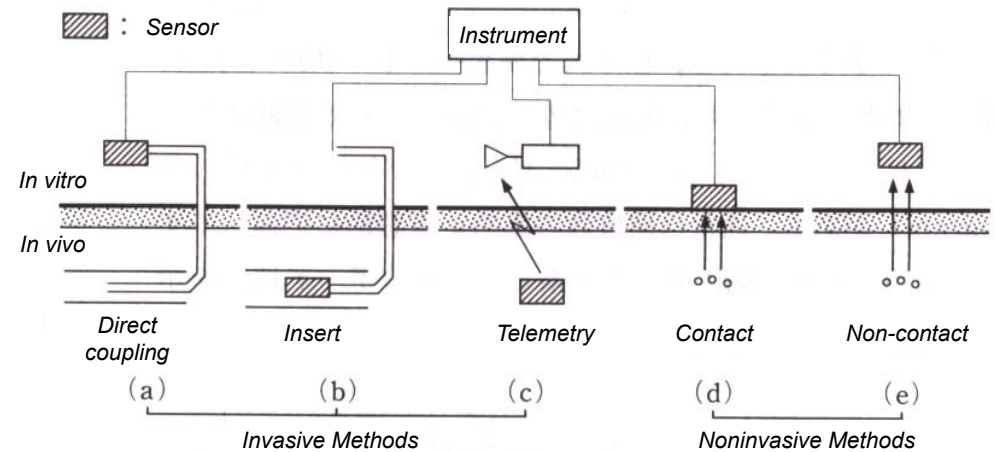
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Biosignal Detection

- Biosignal
 - Physical, chemical, mechanical, thermal, electrical and magnetic quantities that contain information of health condition in physiology and psychophysiology
- Detection
 - **Transduction** - a procedure by which the quantity that characterizes the property or state of an object was sensed or transduced
 - **Conditioning** - an analogical or digital procedure of obtaining wanted information or signal components from the above object quantity

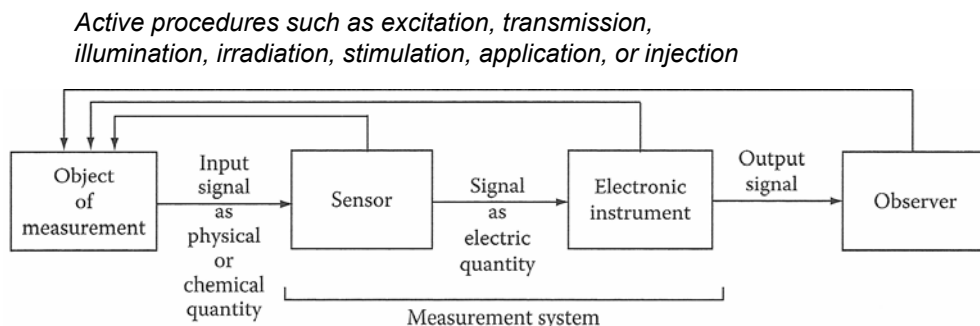
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Invasive and Noninvasive



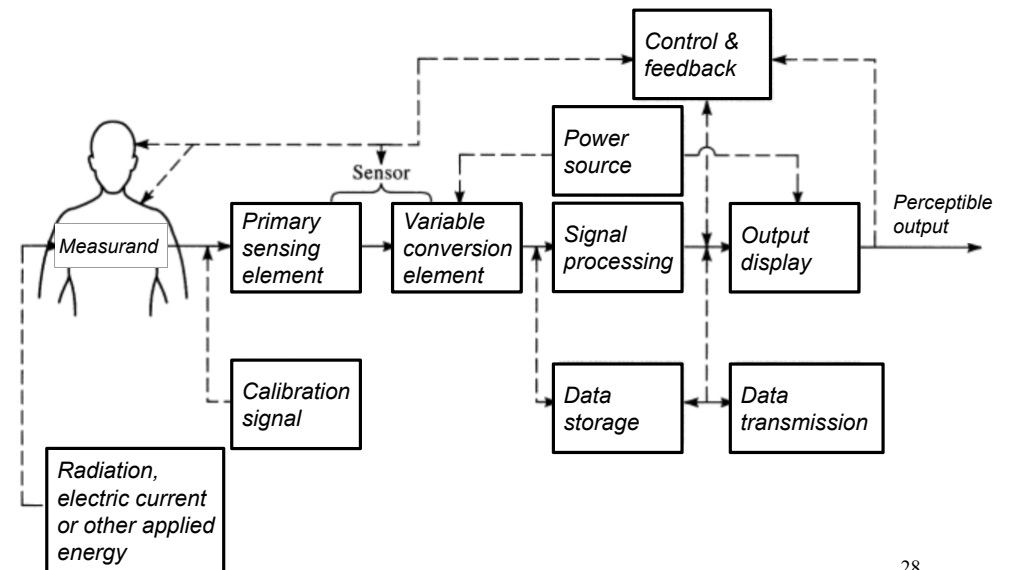
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Measurement Process



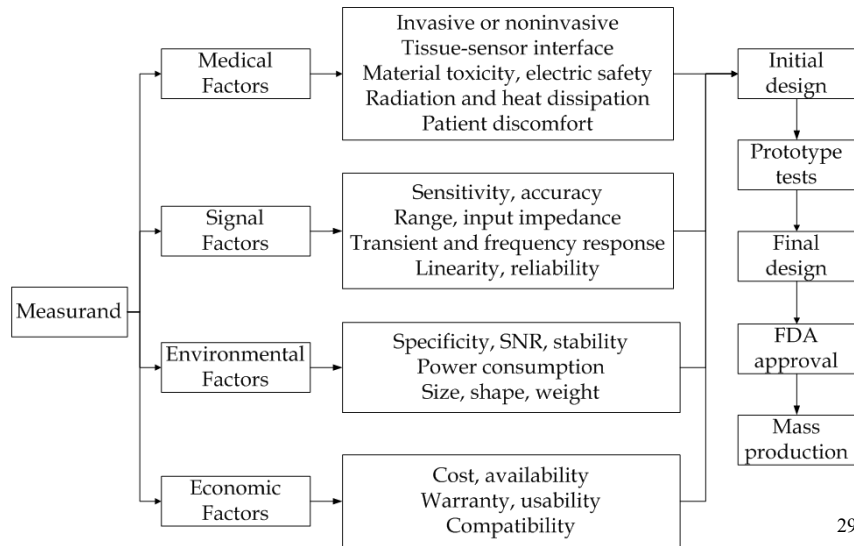
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System Diagram



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R&D Process



Particularities

- Safety in electromagnetism, heat, radiation, vibration
- Minimum disturbance to the organs, tissues and physiological conditions
- Minimum constrained, pain and uncomfortable
- High stability in biophysical and biochemical aspects
- High biological affinity
- Inherent variability among individuals
- Wide response in frequency domain

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General Performance

- Static characteristics
 - The performance of instruments for DC or very low frequency inputs.
 - Some sensors, such as piezoelectric devices, respond only to time-varying inputs and have no static characteristics.
- Dynamic characteristics
 - The performance of instruments for a transient or higher frequency inputs.
 - Differential and/or integral equations are used.

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Static Characteristics - 1

- Accuracy
 - The difference between the true value and the measured value divided by the true value (reference)
- Precision
 - The number of distinguishable alternatives from which a given result is selected
- Resolution
 - The least value of the object quantity that can be distinguished at the output of the measurement system
- Reproducibility or repeatability
 - The ability to give the same output for equal inputs over time
- Sensitivity
 - The ratio of the incremental output quantity to the incremental input quantity

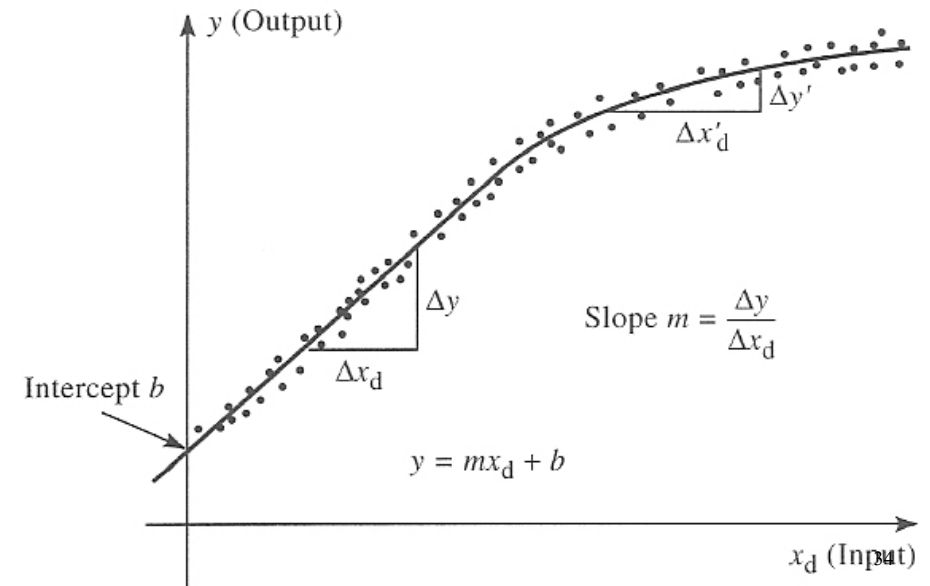
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Static Characteristics - 2

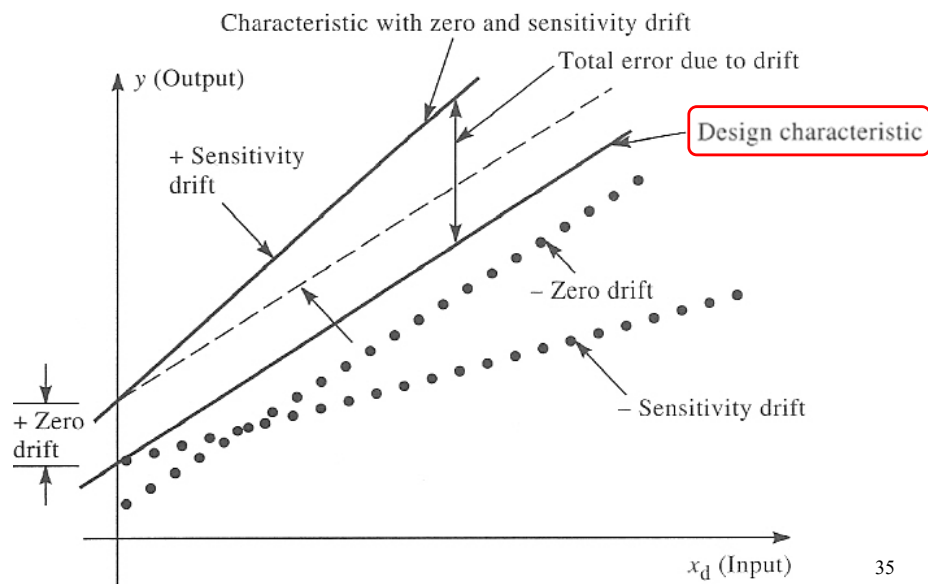
- **Linearity**
 - Response property of outputs to addition and multiplication of inputs
- **Range**
 - Minimal resolvable inputs – a lower bound on the quantity to be measured
 - Measurement range – the maximal allowable change of the object quantity that give the nominal performance
- **Input impedance**
 - The ratio of the phasor equivalent of a steady-state sinusoidal effort input variable (voltage, force, pressure) to the phasor equivalent of a steady-state sinusoidal flow input variable (current, velocity, flow)
- **Hysteresis**
 - The input-output relation depends on the direction and the range of successive input values

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Sensitivity Change

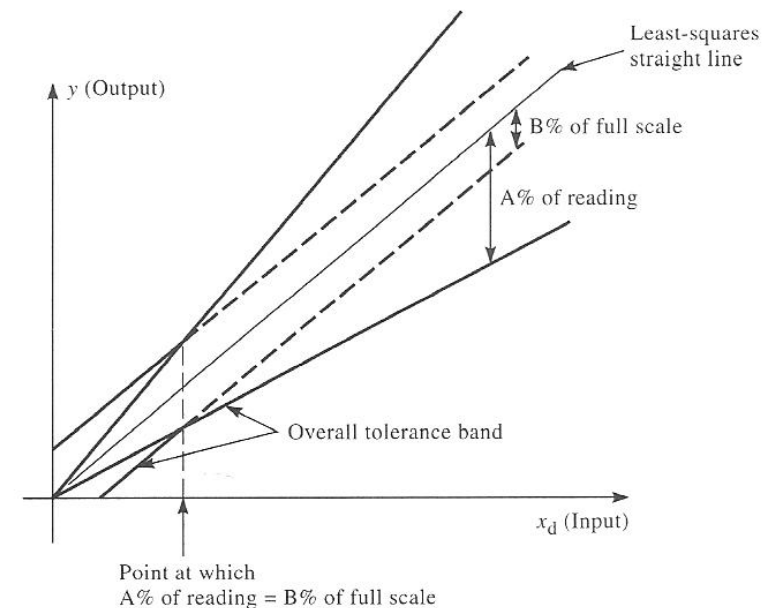


Sensitivity Drift



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Linearity



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Input Impedance

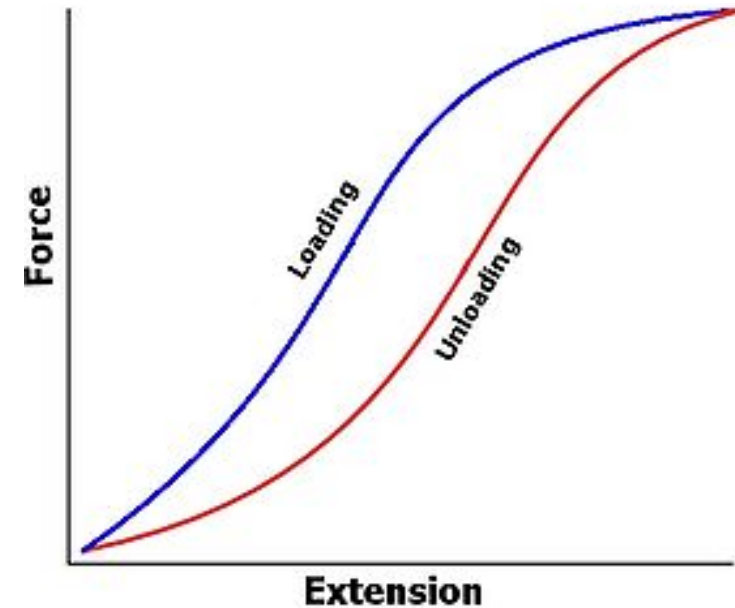
- The degree to which instruments disturb the quantity being measured → smaller=better
- X_{d1} – desired input quantity we seek to measure
- X_{d2} – implicit input quantity to be required by instruments
- Generalized input impedance Z_x → larger=better

$$Z_x = \frac{X_{d1}}{X_{d2}} = \frac{\text{effort_variable}}{\text{flow_variable}}$$

- Power $P = X_{d1} * X_{d2}$ → smaller=better
 - instantaneous rate at which energy is transferred across the tissue-sensor interface

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Hysteresis



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Dynamic Characteristics

- Transfer functions
 - 0th order, 1st order, 2nd order
- Linear and nonlinear systems
 - Linear system – the response to simultaneous inputs is the sum of their independent inputs
 - Nonlinear system – higher harmonics appear but close to linear system in small range
- Frequency response
 - The distribution of the amplitude and the phase shift of the output to sinusoidal inputs of unit amplitude over the whole frequency range
- Time parameters
 - Time constant, response time, rise time, settling time, time delay

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Transfer Function

Differential equation

$$a_n \frac{d^n y(t)}{dt^n} + \dots + a_1 \frac{dy(t)}{dt} + a_0 y(t) = b_m \frac{d^m x(t)}{dt^m} + \dots + b_1 \frac{dx(t)}{dt} + b_0 x(t)$$

Laplace transform

$$\frac{Y(s)}{X(s)} = \frac{b_m s^m + \dots + b_1 s + b_0}{a_n s^n + \dots + a_1 s + a_0}$$

When $s = j\omega$

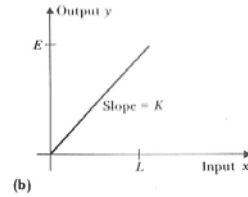
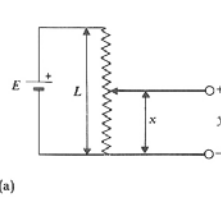
$$\frac{Y(j\omega)}{X(j\omega)} = \frac{b_m (j\omega)^m + \dots + b_1 (j\omega) + b_0}{a_n (j\omega)^n + \dots + a_1 (j\omega) + a_0}$$

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Zero-order System

Differential equation

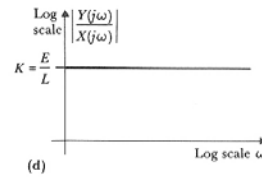
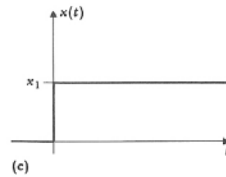
$$a_0 y(t) = x(t)$$



Static sensitivity

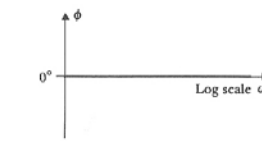
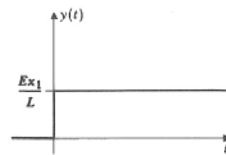
$$\frac{1}{a_0} = K$$

Input



Constant

Output



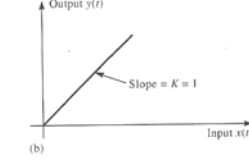
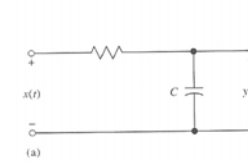
Zero phase shift

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First-order System

Differential equation

$$a_1 \frac{dy(t)}{dt} + a_0 y(t) = x(t)$$

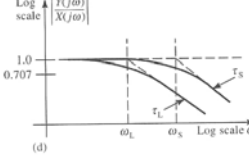
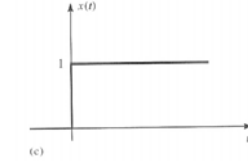


Static sensitivity

$$\frac{1}{a_0} = K$$

Step response

$$y(t) = K(1 - e^{-t/\tau})$$

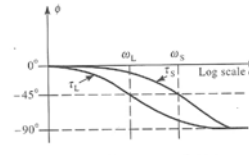
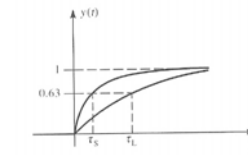


Cutoff frequency

$$\omega = \frac{1}{\tau}$$

Time constant

$$\tau = \frac{a_1}{a_0}$$

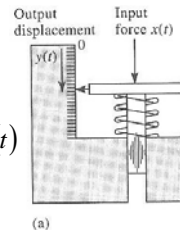


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Second-order System

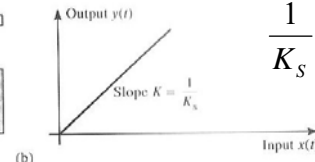
Differential equation

$$a_2 \frac{d^2 y(t)}{dt^2} + a_1 \frac{dy(t)}{dt} + a_0 y(t) = x(t)$$



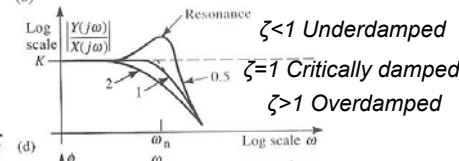
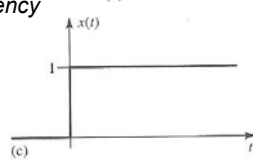
Static sensitivity

$$\frac{1}{K_s} = \frac{1}{a_0} = K$$



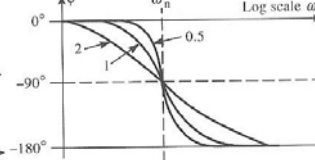
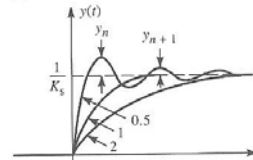
Undamped natural frequency

$$\omega_n = \sqrt{\frac{a_0}{a_2}}$$



Damping ratio

$$\zeta = \frac{a_1}{2\sqrt{a_0 a_2}}$$



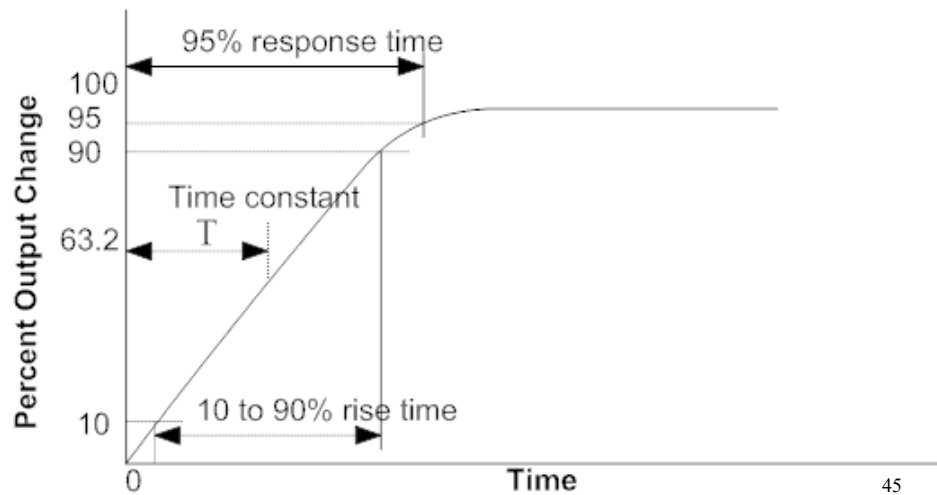
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Time Parameters

- Time constant
 - 1st order system, time to 63.2% of the final value in step response
- Response time
 - time to 95% of the final value
- Rise time
 - 2nd order system, time interval from 10% to 90% of the final value
- Settling time
 - 2nd order system, time to settle within a definite range, ex. $\pm 5\%$, near the final value
- Time delay
 - time to output after input is applied
 - phase angle varies with frequency – the delay is not constant in frequency domain

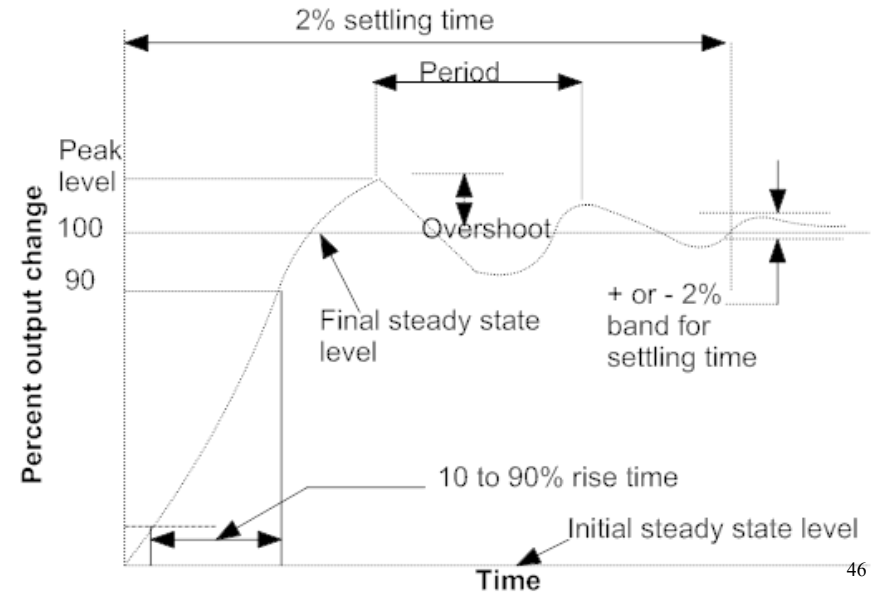
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First-order System



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Second-order System



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Amplitude and Power

- Peak-to-peak value $\max(x(t)) - \min(x(t))$
 - Difference between the maximal peak and the minimal valley
- Root-Mean-Square (RMS) amplitude
 - Root of average squared signal over time $\sqrt{\overline{x(t)^2}}$
- Power
 - Average squared signal over time $\overline{x(t)^2}$

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Power Spectrum

- Distribution of signal power over frequency
- Fourier series of any periodic function of time

$$x(t) = \sum_{n=1}^{\infty} (A_n \cos(n\omega_0 t) + B_n \sin(n\omega_0 t)) \quad \text{where } \omega_0 = \frac{2\pi}{T}$$
- Total power $\overline{x(t)^2} = \frac{1}{2} \sum_{n=1}^{\infty} (A_n^2 + B_n^2)$
- Fourier transform of any function of time

$$X(\omega) = \int_{-\infty}^{+\infty} x(t) e^{-j\omega t} dt$$
- Total power $\overline{x(t)^2} = \frac{1}{2\pi} \int_0^{\infty} |X(\omega)|^2 d\omega$

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Signal and Noise

- Signal
 - the component of a variable that contains information about the object quantity
- Noise
 - a component unrelated to the object quantity
- Signal ↔ Noise
 - not defined by physical nature but by the intention of the observer
- Signal-to-Noise Ratio (SNR)

$$SNR(\text{dB}) = 10 \log_{10} \frac{P_S}{P_N} = 20 \log_{10} \frac{A_S}{A_N}$$

- P and A indicate power and RMS amplitude, respectively

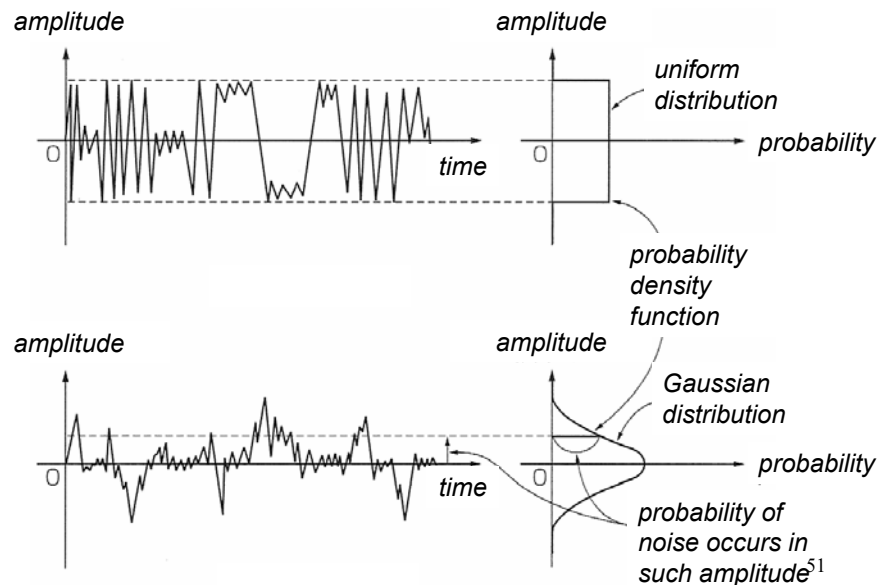
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Types of Noise

- Thermal Noise
 - Random thermal agitation relevant to temperature
 - Uniform distribution of power density
- 1/f Noise
 - Many natural phenomena
 - Power density is inversely proportional to the frequency
- Interference
 - Electromagnetic coupling - power line, fluorescent lamps
- Artifact
 - Superimposed on the object quantity and caused by external factors such as motion – skin-electrode contact

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Distribution of Noise



Absolute Quantity

- Standard
 - Intrinsic standards such as mercury column and gravity of the earth for pressure, ice point of pure water and melting point of gallium for temperature
 - Reliable instruments such as crystal-resonator temperature sensors for body temperature thermometer
- Calibration
 - Nonlinear system – many points
 - Linear system – two points
 - Curve fitting in the sense of least squared errors between input and output
- Accuracy
 - How close the measured value is to the true value
- Error
 - Difference between the measured value and the true value

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Types of Error

- Random error
 - Appears unpredictably in repeated measurements
 - Averaging is an effective way to reduce random errors
- Systematic error
 - The bias from the true value appearing equally in repeated measurements of the same object quantity
 - Origins – drift, improper calibration, uncorrected nonlinearity, round down in digital data
- Dynamic error
 - Occurring from imperfect dynamic characteristics when the object quantity varies so quickly that the output of the measurement system does not follow the change of the input
- Quantization error
 - The difference between the original analog value and the converted digital value during conversion of an analog value to a digital value

Quantization Error

